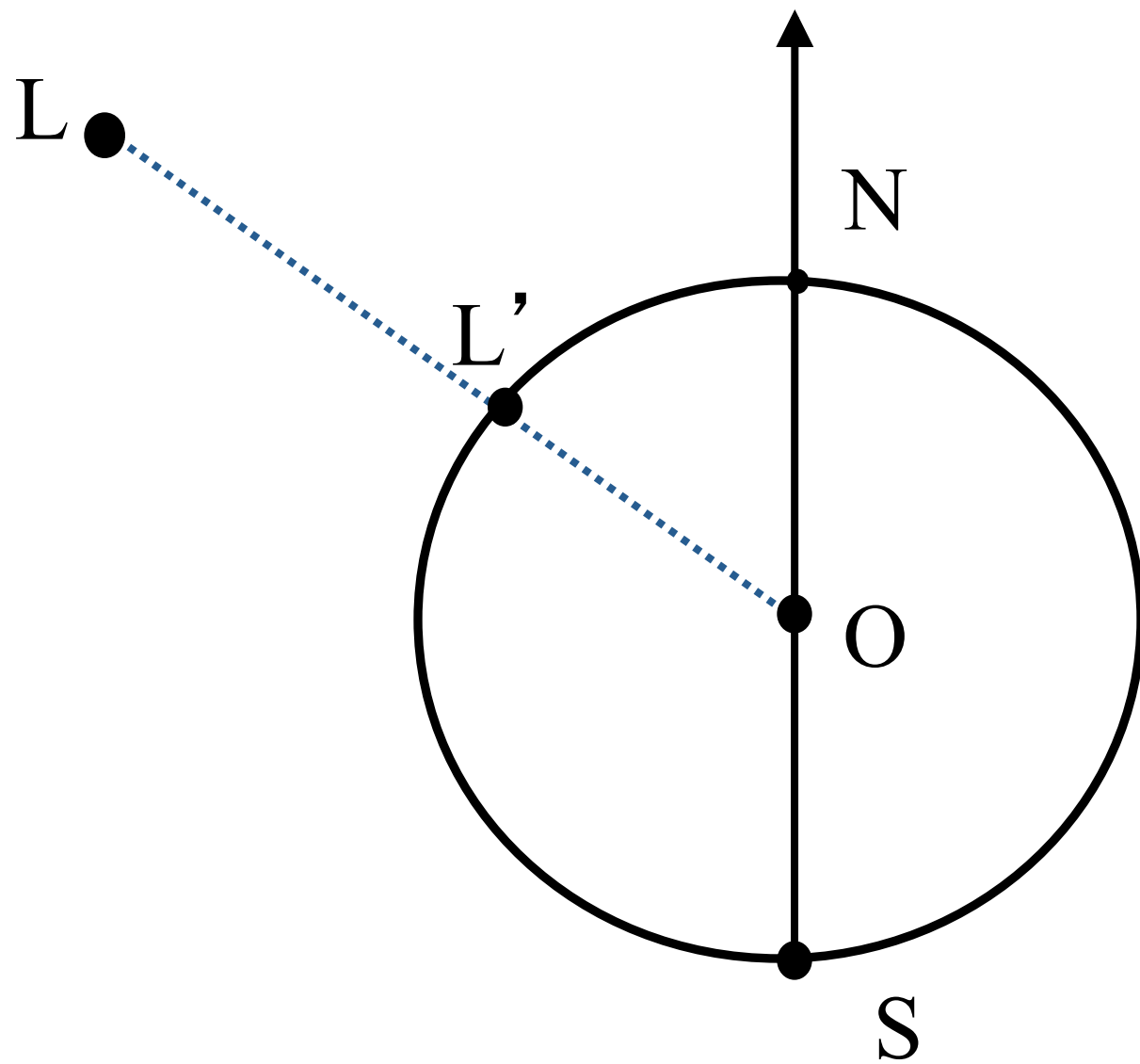
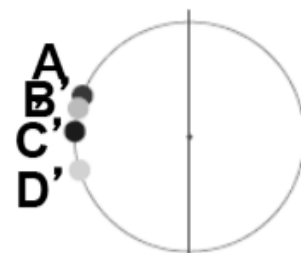
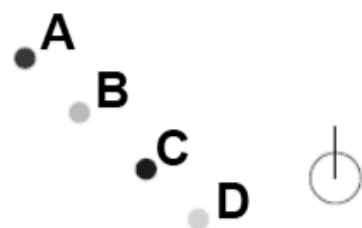
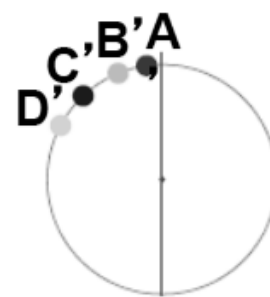
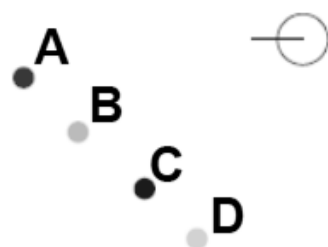
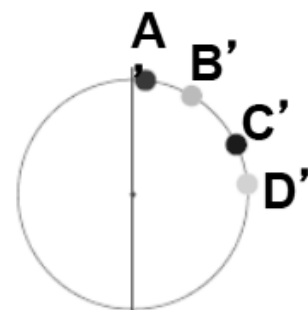
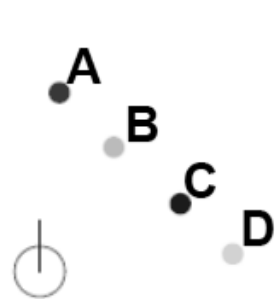
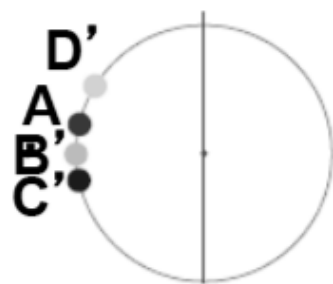
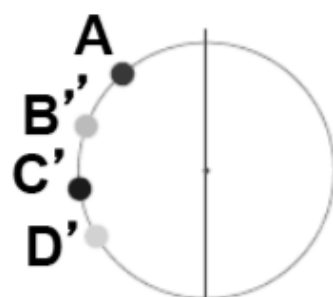
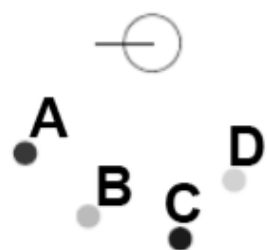
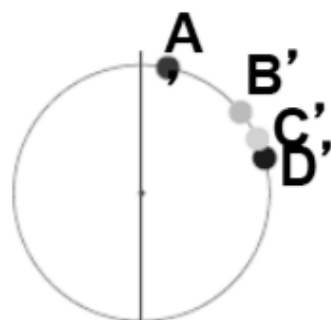
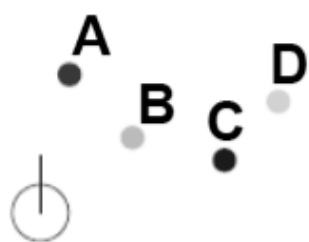


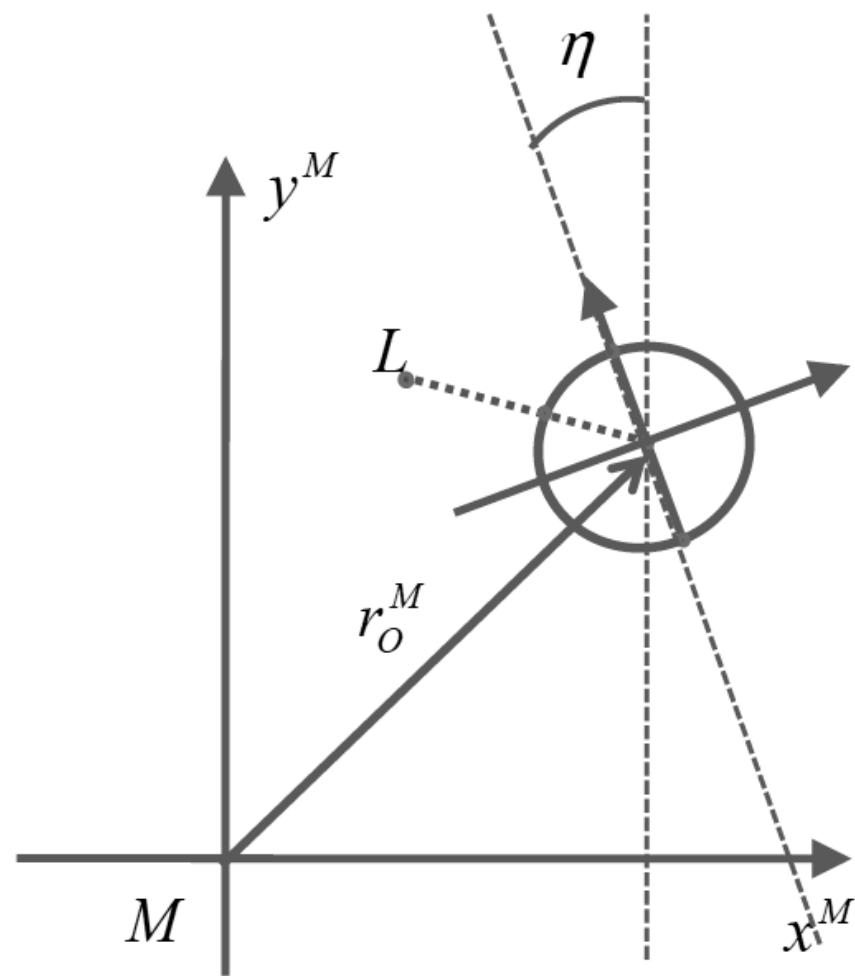
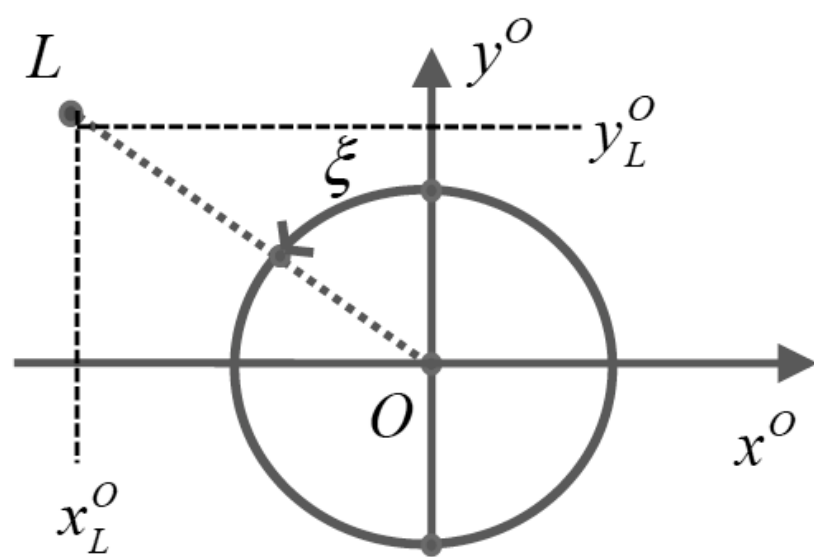


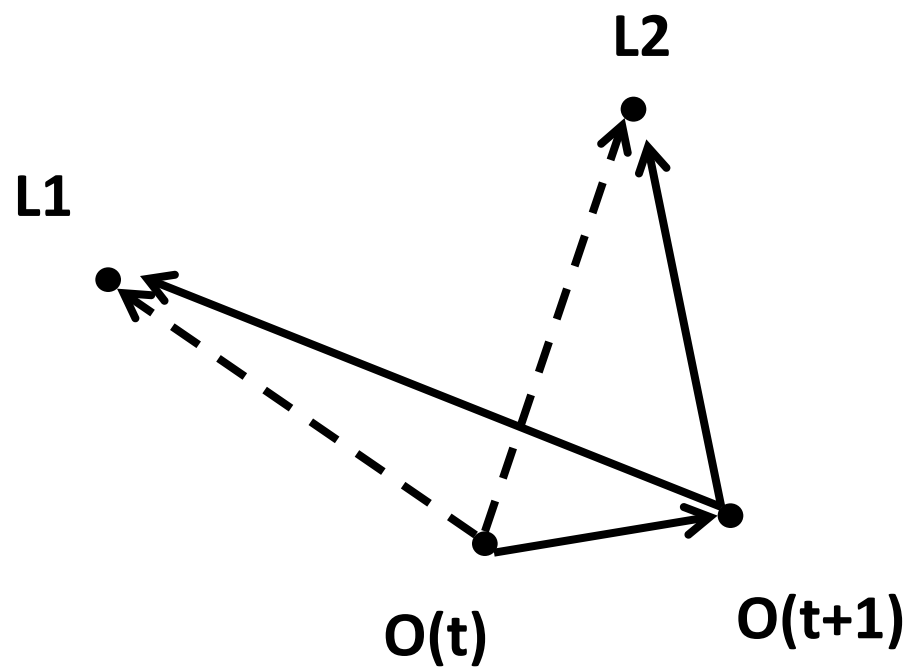
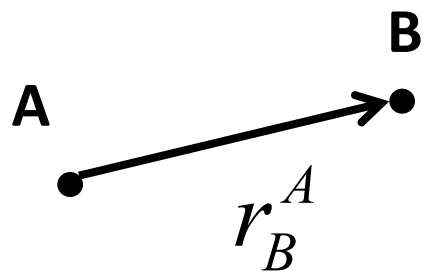
Space

Eye View

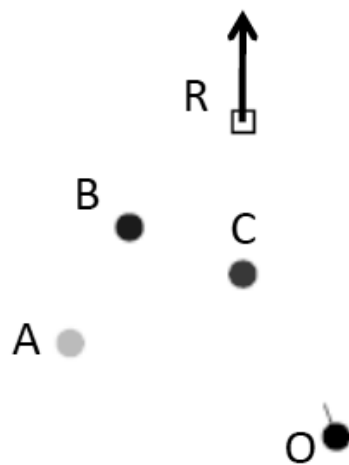




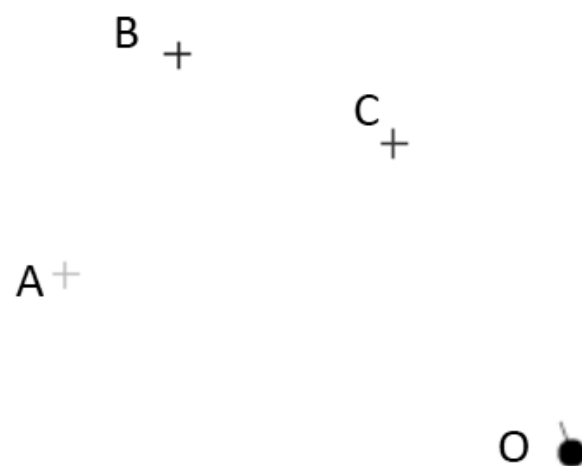




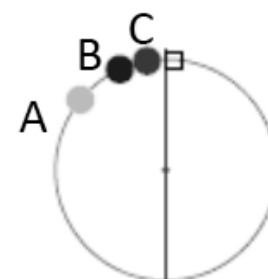
SPACE

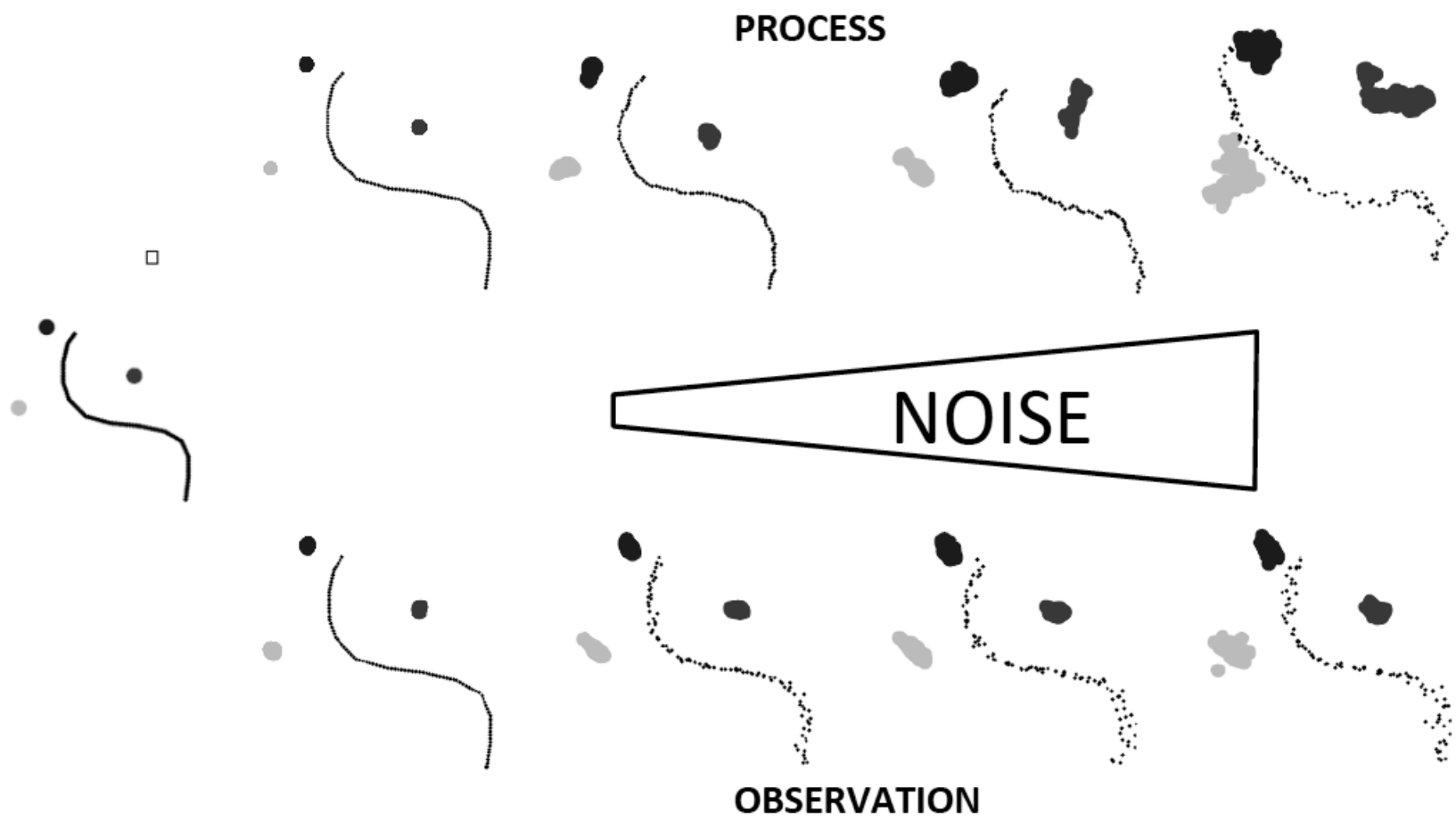


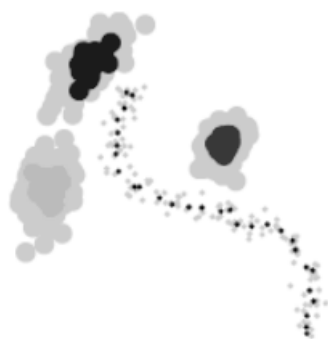
MODEL



EYE







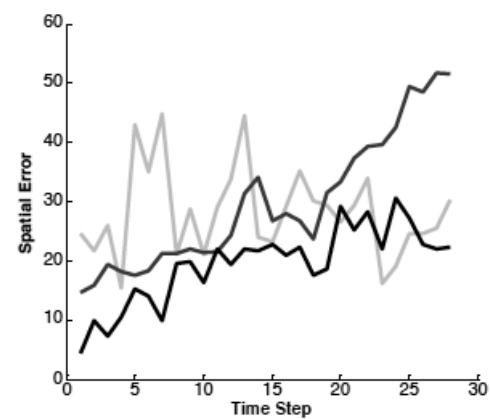
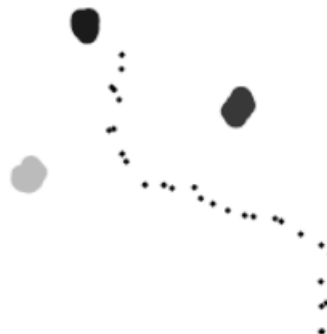
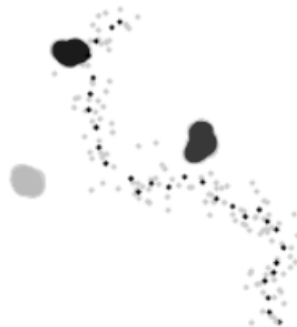
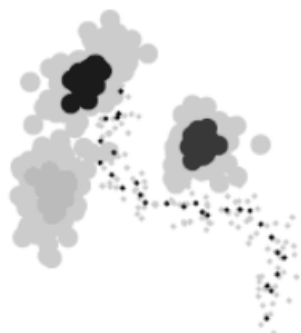
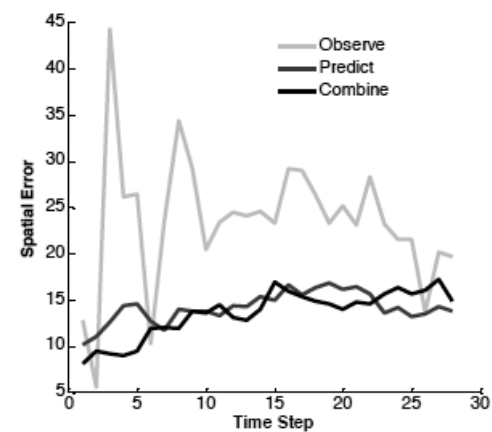
Observation



Prediction



Combined



$$state = \begin{bmatrix} \mathbf{r}_0 \\ \mathbf{r}_1 \\ \mathbf{r}_2 \end{bmatrix}$$

